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SOME BOUNDS ON BALANCED BLOCK DESIGNS.(U)  
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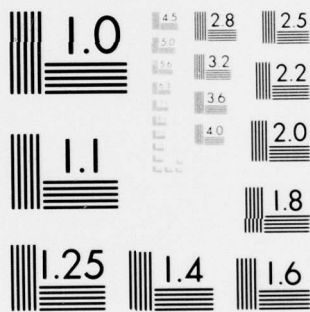
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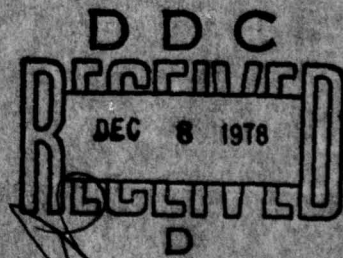
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## Some bounds on Balanced Block Designs

by

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Some bounds on balanced block designs

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Abstract

Bounds on the latent root of the C-matrix and the number of blocks for a variance-balanced block design are given. These results include the well known results as special cases.

# Some bounds on balanced block designs<sup>1)</sup>

Sanpei Kageyama<sup>2)</sup> and Takumi Tsuji

## 1. Introduction

Consider  $v$  treatments arranged in  $b$  blocks with the  $j$ -th block being of size  $k_j$  ( $j = 1, 2, \dots, b$ ) in a block design with incidence matrix  $N = \|n_{ij}\|$  such that the  $i$ -th treatment occurs  $r_i$  times ( $i = 1, 2, \dots, v$ ) and the  $i$ -th treatment occurs in the  $j$ -th block  $n_{ij}$  times, where  $n_{ij}$  can take any of the values,  $0, 1, 2, \dots, n-1$ . Such a design is called an  $n$ -ary block design. If  $n = 2$ , the design is called a binary block design. Let  $T_i$  be the total yield for the  $i$ -th treatment and  $B_j$  that for the  $j$ -th block. On writing  $T' = (T_1, \dots, T_v)$  and  $B' = (B_1, \dots, B_b)$  in matrix notation, the adjusted intrablock normal equations for estimating the vector of treatment effects  $t$  can be written under the usual assumptions as

$$Q = C \hat{t} ,$$

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where  $\hat{t}$  is the estimate of  $t$ ,

$$Q = T - N \text{diag}\{k_1^{-1}, k_2^{-1}, \dots, k_b^{-1}\} B ,$$

$$C = \text{diag}\{r_1, r_2, \dots, r_v\} - N \text{diag}\{k_1^{-1}, k_2^{-1}, \dots, k_b^{-1}\} N' ,$$

and  $\text{diag}$  stands for a diagonal matrix and  $A'$  is the transpose of the matrix  $A$ , and further let  $\text{diag}\{r_1, r_2, \dots, r_v\} = D_r$  and  $\text{diag}\{k_1, k_2, \dots, k_b\} = D_k$ . The matrix  $C$  is well known as the  $C$ -matrix of a block design.

Since each row (or column) of  $C$  adds up to zero, the rank of  $C$  is at most  $v-1$ , and  $(v^{-1/2}, v^{-1/2}, \dots, v^{-1/2})$  is the latent vector corresponding to the zero root. If the rank of  $C$  is  $v-1$ , the design is said to be connected (cf. [3]). We shall deal only with connected designs throughout this paper.

A block design is said to be balanced if every elementary contrast of treatments is estimated with the same variance (cf. [11]). In this sense, this design is also called a variance-balanced block (BB) design. Furthermore, it is known (cf. [5], [6], [7], [8], [9], [10], [11]) that an  $n$ -ary BB design with parameters  $v$  ( $\geq 2$ ),  $b$  ( $> 0$ ),  $r_i$  ( $> 0$ ),  $k_j$  ( $\geq 2$ ) ( $i = 1, 2, \dots, v$ ;  $j = 1, 2, \dots, b$ ) can be given by an incidence matrix  $N$  satisfying

$$(C =) D_r - N D_k^{-1} N' = \rho \{I_v - (1/v) G_v\} ,$$

where  $\rho = \{ \sum_{i=1}^v r_i - \sum_{j=1}^b (1/k_j) \sum_{i=1}^v n_{ij}^2 \} / (v-1)$ ,  $I_v$  is the unit matrix of order  $v$ ,  $G_v = E_{v \times v}$  and  $E_{\ell \times s}$  is an  $\ell \times s$  matrix with positive unit elements everywhere. Note that for a binary BB design,  $\rho = (\sum_{i=1}^v r_i - b) / (v-1)$ .

The literature of block designs contains many articles exclusively related to BB designs. The interested reader can refer, for example, to [5], [6], [7], [8], [9], [10] and [11] for details. Kageyama [7], [8] and [9] has extensively dealt with combinatorial properties and constructions of binary BB designs. In this paper, for an  $n$ -ary BB design some bounds on the latent root of the  $C$ -matrix and the number of blocks are given. These results include the results well known from various aspects of experimental designs.

Finally, since a design uniquely determines its incidence matrix and vice versa, both a design and its incidence matrix are denoted by the same symbol throughout this paper.

## 2. Bounds on the latent root and the number of blocks

Let rearrange blocks of a block design  $N$  as  $N = [N_1 : N_2]$ , where  $N_i$ 's ( $i = 1, 2$ ) consist of some blocks. Then the  $C$ -matrix of  $N$  can be shown to be

$$C = C_1 + C_2 ,$$

where  $C_i$ 's ( $i = 1, 2$ ) are the  $C$ -matrices of  $N_i$ 's. Hence, for example, if  $C_1 = 0$ , then  $N_1$  does not influence discussions on the  $C$ -matrix of the design  $N$ . Hereinafter we will exclude from our consideration a collection of blocks whose  $C$ -matrix is a zero matrix. This collection of blocks can be characterized as follows.

Lemma A. The  $C$ -matrix of a collection of some blocks is a zero matrix if and only if each block contains at most only one treatment  $\alpha$  ( $\geq 0$ ) times.

Proof. For a collection of some blocks, let the respective numbers of treatments and blocks be  $v^*$  and  $b^*$ , and further let the replication numbers of treatments and the sizes of blocks be  $r_i^*$  ( $i = 1, 2, \dots, v^*$ ) and  $k_j^*$  ( $j = 1, 2, \dots, b^*$ ), respectively. We denote the incidence matrix of a collection of  $b^*$  blocks by  $N^* = \|n_{ij}\|$  ( $i = 1, 2, \dots, v^*$ ;  $j = 1, 2, \dots, b^*$ ). (Necessity part):  $C = \text{diag}\{r_1^*, r_2^*, \dots, r_{v^*}^*\} - N^* \text{diag}\{k_1^{*-1}, k_2^{*-1}, \dots, k_{b^*}^{*-1}\} N^{*'} = O_{v^* \times v^*}$  is equivalent to  $\text{diag}\{r_1^*, r_2^*, \dots, r_{v^*}^*\} = N^* \text{diag}\{k_1^{*-1}, k_2^{*-1}, \dots, k_{b^*}^{*-1}\} N^{*-1}$  which is expressed as

$$(2.1) \quad r_i^* = \sum_{j=1}^{b^*} n_{ij}^2 / k_j^* \quad \text{for all } i = 1, 2, \dots, v^*,$$

$$(2.2) \quad 0 = \sum_{j=1}^{b^*} n_{ij} n_{i'j} / k_j^* \quad \text{for all } i, i' \ (i \neq i') = 1, 2, \dots, v^*,$$

where  $O_{s \times t}$  is an  $s \times t$  matrix whose elements are all zero. Since  $k_j^* > 0$  for all  $j$ , (2.2) yields  $n_{i1} n_{i'1} = n_{i2} n_{i'2} = \dots = n_{ib^*} n_{i'b^*} = 0$  for all  $i, i'$  ( $i \neq i'$ ) which imply that each block contains at most only one treatment  $\alpha$  times for some  $\alpha$  ( $\geq 0$ ). (Sufficiency part): It obviously follows from the assumption that relations (2.1) and (2.2) holds. Then we have  $C = O_{v^* \times v^*}$ .

Remark 2.1. From Lemma A, each block of a BB design which will be considered here contains at least two distinct treatments.

The latent roots of the C-matrix play an important role in problems concerning efficiency and analysis for block designs. Especially, as a bound on the latent root,  $\theta$ , <sup>say,</sup> for the C-matrix, it is known

(cf. [7], [9]) that  $0 \leq \max_{1 \leq i \leq v} r_i$  for a general block design. The problem on an improvement of this bound is first considered in this section for the following two cases.

For the convenience of notation, we further let  $\max r_i = \max_{1 \leq i \leq v} r_i$ ,  $\min r_i = \min_{1 \leq i \leq v} r_i$ ,  $\max k_j = \max_{1 \leq j \leq b} k_j$  and  $\min k_j = \min_{1 \leq j \leq b} k_j$ .

### 2.1. For binary BB designs

We first obtain the following bound on the latent root of the C-matrix.

Theorem 2.1.1. For a binary BB design with parameters  $v, b, r_i, k_j$  ( $i = 1, 2, \dots, v; j = 1, 2, \dots, b$ ) in which  $C = \rho\{I_v - (1/v)G_v\}$ ,

$$\frac{v}{v-1}(\max r_i)(1 - \frac{1}{\min k_j}) \leq \rho \leq \frac{v}{v-1}(\min r_i)(1 - \frac{1}{\max k_j})$$

holds.

Proof. Comparing any diagonal element of the C-matrix ( $= D_r - ND_k^{-1}N'$ ) yields:

$$\begin{aligned} r_i - \rho(1 - \frac{1}{v}) &= \frac{n_{i1}}{k_1} + \dots + \frac{n_{ib}}{k_b} \\ &\geq \frac{n_{i1} + \dots + n_{ib}}{\max k_j} \end{aligned}$$

$$= r_i / (\max k_j), \quad i = 1, 2, \dots, v,$$

which implies  $\rho \leq \{v/(v-1)\}r_i\{1 - 1/(\max k_j)\}$  for all  $i = 1, 2, \dots, v$ .

Hence we get

$$(2.3) \quad \rho \leq \frac{v}{v-1} (\min r_i) \left(1 - \frac{1}{\max k_j}\right) .$$

On the other hand,

$$\begin{aligned} r_i - \rho \left(1 - \frac{1}{v}\right) &= \frac{n_{i1}}{k_1} + \dots + \frac{n_{ib}}{k_b} \\ &\leq \frac{n_{i1} + \dots + n_{ib}}{\min k_j} = r_i / (\min k_j) \end{aligned}$$

which yields  $\rho \geq \{v/(v-1)\} r_i \{1 - 1/(\min k_j)\}$  for all  $i = 1, 2, \dots, v$ .

Hence we get

$$(2.4) \quad \rho \geq \frac{v}{v-1} (\max r_i) \left(1 - \frac{1}{\min k_j}\right) .$$

Thus, relations (2.3) and (2.4) imply the required result.

Remark 2.2. The upper bound on  $\rho$  in Theorem 2.1.1 is attainable if the design is equiblock-sized (in which case, it is obvious that the design is a balanced incomplete block (BIB) design).

For a binary BB design we have the exact value of  $\rho$ , i.e.,  $\rho = (\sum_{i=1}^n r_i - b)/(v-1)$ . In this sense, the very bound of Theorem 2.1.1 may make no sense practically. However, Theorem 2.1.1 yields a strong restriction on replication numbers  $r_i$  ( $i = 1, 2, \dots, v$ ) as follows.

Corollary 2.1.1. For a binary BB design with parameters  $v, b, r_i$  and  $k_j$  for  $i = 1, 2, \dots, v$  and  $j = 1, 2, \dots, b$ ,



$$\frac{\min r_i}{\max r_i} \geq \left( \frac{\max k_j}{\max k_j - 1} \right) \left( \frac{\min k_j - 1}{\min k_j} \right) .$$

Remark 2.3. Since  $\min k_j \geq 2$  and  $v \geq \max k_j$ , Corollary 2.1.1 further implies that

$$\frac{\min r_i}{\max r_i} \geq \frac{\max k_j}{2(\max k_j - 1)} \geq \frac{v}{2(v-1)} .$$

Since  $v \geq \max k_j$  for a binary design, Theorem 2.1.1 yields

Corollary 2.1.2. For a binary BB design with parameters  $v, b, r_i$  and  $k_j$  ( $i = 1, 2, \dots, v; j = 1, 2, \dots, b$ ) in which  $C = \rho\{I_V - (1/v)G_V\}$ ,

$$\rho \leq \min r_i .$$

This upper bound is not superior to the upper bound in Theorem 2.1.1. When  $v = \max k_j$ , both the bounds are the same. However, the bound in Corollary 2.1.2 is very simple and practical. Thus, this bound appears to be worth describing.

## 2.2. For n-ary BB designs

We here consider bounds on the latent root of the C-matrix for an n-ary BB design. First of all, the bound in Corollary 2.1.2 is not generally valid for an n-ary BB design. For example, we can produce a BB design with parameters  $v = 3, b = 5, r_i = 4$  or  $9, k_j = 4$  or  $6$ , whose incidence matrix is given by

$$\begin{bmatrix} 1 & 1 & 1 & 1 & 0 \\ 3 & 3 & 0 & 0 & 3 \\ 0 & 0 & 3 & 3 & 3 \end{bmatrix} \quad \text{and} \quad C = (9/2)\{I_3 - (1/3)G_3\} .$$



In this case,  $\rho = 9/2 > \min r_i = 4$ .

We then describe an upper bound on the latent root of the C-matrix for an n-ary BB design.

Theorem 2.2.1. For an n-ary BB design with parameters  $v, b, r_i, k_j$  ( $i = 1, 2, \dots, v; j = 1, 2, \dots, b$ ) in which  $C = \rho\{I_v - (1/v)G_v\}$  such that  $r_1 \leq r_2 \leq \dots \leq r_v$ ,

$$\rho \leq \min\left\{\frac{r_1+r_2}{2}, \frac{v}{v-1}r_1\left(1 - \frac{1}{\max k_j}\right)\right\}.$$

Proof. An argument for the former in the proof of Theorem 2.1.1 still holds for an n-ary BB design. We then have  $\rho \leq \{v/(v-1)\}r_1[1 - 1/(\max k_j)]$ . Next, from the form of the C-matrix, i.e.,  $D_r - ND_k^{-1}N'$  =  $\rho\{I_v - (1/v)G_v\}$ , we get that for any column vector  $\underline{x}$ ,

$$\underline{x}'(D_r - ND_k^{-1}N')\underline{x} = \rho\underline{x}'\{I_v - (1/v)G_v\}\underline{x}$$

which implies that, letting  $\underline{x}' = (1/\sqrt{2})(1, -1, 0, \dots, 0)$ ,

$$\rho = \frac{1}{2}(r_1 + r_2) - \frac{1}{2}\left\{\sum_{j=1}^b (n_{1j} - n_{2j})^2/k_j\right\}$$

which yields  $\rho \leq (r_1 + r_2)/2$ . Hence the proof is completed.

Remark 2.4. One of upper bounds in Theorem 2.2.1,  $\rho \leq \{v/(v-1)\}(\min r_i)[1 - 1/(\max k_j)]$ , attains the bound if  $k_1 = k_2 = \dots = k_b$  and any row (of N) in which  $\min r_i$  is attained is binary.

Remark 2.5. From a method similar to Theorem 2.1.1, we can give a lower bound on  $\rho$  as follows:  $\rho \geq \{v/(v-1)\} \max_{1 \leq i \leq v} [r_i\{1 - r_i/(\min k_j)\}]$

for an  $n$ -ary BB design. However, this bound is meaningful only if there exists an  $r_i$  such that  $r_i < \min k_j$ .

When  $\max k_j \leq v$  in Theorem 2.2.1, it is clear that

$$\frac{r_1 + r_2}{2} \geq r_1 \geq \frac{v}{v-1} r_1 \left(1 - \frac{1}{\max k_j}\right).$$

Then we get

Corollary 2.2.1. For an  $n$ -ary BB design with parameters  $v, b, r_i, k_j$  in which  $C = \rho\{I_v - (1/v)G_v\}$  such that  $r_1 \leq r_2 \leq \dots \leq r_v$ ,

- (i) if  $r_1 = r_2$ ,  $\rho \leq \min\{r_1, \frac{v}{v-1} r_1 (1 - 1/(\max k_j))\}$ ,
- (ii) if  $v \geq \max k_j$ ,  $\rho \leq \frac{v}{v-1} (\min_{1 \leq i \leq v} r_i) (1 - \frac{1}{\max k_j}) \leq \min r_i$ .

Remark 2.6. Each of two conditions,  $r_1 = r_2$  and  $v \geq \max k_j$ , is a sufficient condition for the validity of the bound  $\rho \leq \min r_i (= r_1)$ . We can give other sufficient conditions. For example, from (i) in Corollary 2.2.1, we have only to consider a case in which the cardinality of set  $\{i: \min_{1 \leq i \leq v} r_i \text{ is attained}\}$  is one (i.e.,  $r_1 < r_2 \leq \dots \leq r_v$ ). In this case, as a sufficient condition for  $\rho \leq r_1$  to be valid, we can present each of the following two conditions: For a BB design  $N = \|n_{ij}\|$ ,

- (a)  $v n_{1j} \geq k_j$  for all  $j$  such that  $n_{1j} > 0$ ;
- (b)  $v \left( \sum_{j=1}^b n_{1j}^2 / k_j \right) \geq r_1$ .

As another upper bound of reflecting certain block structure, we have for an  $n$ -ary BB design

$$(2.5) \quad \rho \leq (v \max_{1 \leq i \neq i' \leq v} \lambda_{ii'}) / (\min k_j) ,$$

where  $\lambda_{ii'} = \sum_{j=1}^b n_{ij} n_{i'j}$ . This can be shown as follows: From Frobenius' theorem (cf. [2], p.66), we have

$$(2.6) \quad \rho \geq 2 \min_{1 \leq i \leq v} c_{ii} + (v-2)d ,$$

where  $c_{ii}$  is the  $i$ -th diagonal element of the  $C$ -matrix and  $d$  is the numerically largest absolute value of off-diagonal elements of  $C$ . Now,

$$\begin{aligned} |d| &= \max_{1 \leq i, i' \leq v} \left\{ \frac{n_{i1} n_{i'1}}{k_1} + \dots + \frac{n_{ib} n_{i'b}}{k_b} \right\} \\ (2.7) \quad &\leq \max_{i, i'} \left\{ \frac{n_{i1} n_{i'1} + \dots + n_{ib} n_{i'b}}{\min k_j} \right\} \\ &= (\max_{i, i'} \lambda_{ii'}) / (\min k_j) , \end{aligned}$$

where  $\lambda_{ii'} = \sum_{j=1}^b n_{ij} n_{i'j}$ . Since  $c_{ii} = \rho(1 - 1/v)$  and  $v \geq 2$ , we get (2.5) from (2.6) and (2.7). However, bound (2.5) may be not relatively good as an upper bound.

Furthermore, we can present mathematically an upper bound on  $\rho$  which gives a partial improvement of Theorem 2.2.1. The following result also plays an important role on an argument (of Section 2.3) providing sufficient conditions for the validity of Fisher's inequality.

**Theorem 2.2.2.** For an  $n$ -ary BB design with parameters  $v, b, r_i, k_j$  ( $i = 1, 2, \dots, v; j = 1, 2, \dots, b$ ) in which  $C = \rho\{I_v - (1/v)G_v\}$ ,

$$\rho \leq \rho_0 ,$$

where  $\rho_0$  is the least positive root of the following polynomial of degree  $v-1$

$$\begin{aligned}
 (2.8) \quad f(\rho) &= |D_r - \rho I_v + (\rho/v) G_v| \\
 &= \frac{(-1)^{v-1}}{v} \left( \sum_{i=1}^v r_i \right) \rho^{v-1} + (-1)^{v-2} \frac{2}{v} \left( \sum_{i < j} r_i r_j \right) \rho^{v-2} \\
 &\quad + (-1)^{v-3} \frac{3}{v} \left( \sum_{i < j < k} r_i r_j r_k \right) \rho^{v-3} + \dots + \frac{v}{v} r_1 r_2 \dots r_v.
 \end{aligned}$$

The proof of this theorem needs some preliminary results. The following two lemmas are available in various books on linear algebra.

Lemma 2.2.1 (cf. [1], p.75). For a real symmetric matrix  $A = \|a_{ij}\|$  of order  $v$ ,  $A$  is positive definite if and only if

$$|A^{(s)}| > 0 \quad \text{for} \quad s = 1, 2, \dots, v,$$

where

$$A^{(s)} = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1s} \\ a_{21} & a_{22} & \dots & a_{2s} \\ \vdots & \vdots & & \vdots \\ a_{s1} & a_{s2} & \dots & a_{ss} \end{bmatrix}.$$

Lemma 2.2.2 (cf. [1], p.117). When  $A$  is a real symmetric matrix and  $B$  is any principal submatrix of  $A$ , the maximal latent root of  $A$  is greater than or equal to the maximal latent root of  $B$ .

Proposition 2.2.1. There exists the least positive root ( $= \rho_0$ , say) of  $f(\rho)$  in (2.8). (i) If  $\rho < \rho_0$ , then  $D_r - \rho I_v + (\rho/v) G_v$  is positive definite. (ii) If  $\rho = \rho_0$ , then  $D_r - \rho I_v + (\rho/v) G_v$  is positive

semidefinite and singular. (iii) If  $\rho > \rho_0$ , then  $D_r - \rho I_v + (\rho/v)G_v$  is not positive semidefinite.

Proof. Let  $A^{(s)} = D_r^{(s)} - \rho I_s + (\rho/v)G_s$  for  $s = 1, 2, \dots, v$  which is a principal submatrix of  $D_r - \rho I_v + (\rho/v)G_v (= ND_k^{-1}N')$ , where  $D_r^{(s)} = \text{diag}\{r_1, r_2, \dots, r_s\}$ . Further, let  $f^{(s)}(\rho) = |A^{(s)}|$  for  $s = 1, 2, \dots, v$ . In particular,  $f^{(v)}(\rho) = f(\rho)$  in (2.8). Now, consider roots of  $f^{(s)}(\rho) = |D_r^{(s)} - \rho\{I_s - (1/v)G_s\}| = 0$  which also yields  $\rho \neq 0$ . Then the nonzero roots of  $f^{(s)}(\rho)$  can be shown to be equivalent to the nonzero roots of the following equation:

$$(2.9) \quad \left| (1/\rho)I_s - D_r^{(s)-1/2} \{I_s - (1/v)G_s\} D_r^{(s)-1/2} \right| = 0$$

for  $s = 1, 2, \dots, v$ . Furthermore,  $D_r^{(s)-1/2} \{I_s - (1/v)G_s\} D_r^{(s)-1/2}$  is positive semidefinite. Hence its latent root,  $1/\rho$ , is real and non-negative, i.e.,  $\rho$  is a positive real number. Hence  $f^{(s)}(\rho)$  has only positive roots. Let  $\rho_0^{(s)}$  be the least positive root of  $f^{(s)}(\rho)$ . Especially,  $\rho_0^{(v)} (= \rho_0, \text{ say})$  is the least positive root of  $f(\rho)$ . In this case, we can show that

$$(2.10) \quad \rho_0^{(1)} \geq \rho_0^{(2)} \geq \dots \geq \rho_0^{(v-1)} \geq \rho_0^{(v)} = \rho_0.$$

This can be given as follows. In (2.9),  $D_r^{(s-1)-1/2} \{I_{s-1} - (1/v)G_{s-1}\} \cdot D_r^{(s-1)-1/2}$  is obviously a principal submatrix of  $D_r^{(s)-1/2} \{I_s - (1/v)G_s\} \cdot D_r^{(s)-1/2}$ . This fact together with Lemma 2.2.2 implies that the maximal latent root of  $D_r^{(s)-1/2} \{I_s - (1/v)G_s\} D_r^{(s)-1/2}$  is greater than or equal to the maximal latent root of  $D_r^{(s-1)-1/2} \{I_{s-1} - (1/v)G_{s-1}\} D_r^{(s-1)-1/2}$ .



This statement yields (2.10).

(i) Since  $f^{(s)}(0) > 0$  and  $f^{(s)}(\rho)$  is a polynomial, if  $\rho < \rho_0$ , then, from the meaning of  $\rho_0$ ,  $f^{(s)}(\rho) > 0$  holds for  $s = 1, 2, \dots, v$ . Hence, from Lemma 2.2.1,  $D_r - \rho I_v + (\rho/v)G_v$  is positive definite.

(ii) If  $\rho = \rho_0$ , then  $f(\rho_0) = 0$ , i.e.,  $D_r - \rho_0 I_v + (\rho_0/v)G_v$  is singular. For any nonzero column vector  $\underline{x}$ , let  $\underline{x}'\{D_r - \rho I_v + (\rho/v)G_v\}\underline{x} = g(\rho : \underline{x})$ . Then  $g(\rho : \underline{x})$  is continuous linear function on  $\rho$  and, from (i),  $g(\rho : \underline{x}) > 0$  for  $\rho < \rho_0$ . Thus,  $g(\rho_0 : \underline{x}) \geq 0$  for any nonzero vector  $\underline{x}$ . Therefore,  $D_r - \rho_0 I_v + (\rho_0/v)G_v$  is positive semidefinite.

(iii) Since  $D_r - \rho_0 I_v + (\rho_0/v)G_v$  is singular, there exists a nonzero column vector  $\underline{x}$  such that  $\{D_r - \rho_0 I_v + (\rho_0/v)G_v\}\underline{x} = \underline{0}$ . In this case, we get

$$\begin{aligned} & \underline{x}'\{D_r - \rho I_v + (\rho/v)G_v\}\underline{x} \\ &= \underline{x}'\{D_r - \rho_0 I_v + (\rho_0/v)G_v\}\underline{x} + (\rho_0 - \rho)\underline{x}'\{I_v - (1/v)G_v\}\underline{x} \\ &= (\rho_0 - \rho)\underline{x}'\{I_v - (1/v)G_v\}\underline{x} \\ &= (\rho_0 - \rho)\underline{x}'\{(1/\rho_0)D_r\}\underline{x} < 0, \end{aligned}$$

since  $\rho > \rho_0$ . Therefore,  $D_r - \rho I_v + (\rho/v)G_v$  is not positive semidefinite.

Proof of Theorem 2.2.2. From the C-matrix of the design,  $D_r - \rho I_v + (\rho/v)G_v = ND_k^{-1}N'$  is positive semidefinite. Hence Proposition 2.2.1 completes the proof.

We also give examples showing the goodness of respective upper bounds in Theorems 2.2.1 and 2.2.2.



Example 2.1. Consider a BB design with parameters  $v = 5$ ,  $b = 8$ ,  $r_i = 4$  or  $8$ ,  $k_j = 3$ , whose incidence matrix is given by

$$\begin{bmatrix} 2 & 2 & 2 & 2 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 1 & 1 & 1 & 0 \\ 0 & 1 & 0 & 0 & 1 & 1 & 0 & 1 \\ 0 & 0 & 1 & 0 & 1 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 & 0 & 1 & 1 & 1 \end{bmatrix} \quad \text{and} \quad C = \frac{10}{3}(I_5 - \frac{1}{5}G_5) .$$

In this case,  $\rho \leq (r_1 + r_2)/2$ ,  $\rho \leq [v/(v-1)]r_1[1 - 1/(\max k_j)]$  and  $\rho \leq \rho_0$  imply  $\rho \leq 4$ ,  $\rho \leq 10/3$  and  $\rho \leq 4$ , respectively. Thus,  $\min r_i = \rho_0$ .

Example 2.2. Consider an example described before Theorem 2.2.1. For this case,  $\rho \leq (r_1 + r_2)/2$ ,  $\rho \leq [v/(v-1)]r_1[1 - 1/(\max k_j)]$  and  $\rho \leq \rho_0$  imply  $\rho \leq 13/2$ ,  $\rho \leq 5$  and  $\rho \leq 54/11$ , respectively.

For a notation of Proposition 2.2.1, we have  $\rho_0^{(1)} = \{v/(v-1)\}r_1$  and  $\rho_0^{(2)} = \{(v-1)(r_1 + r_2) - \sqrt{(v-1)^2(r_1 + r_2)^2 - 4r_1r_2v(v-2)}\}/2(v-2)$   
 $= \{(v-1)(r_1 + r_2) - \sqrt{(v-1)^2(r_1 - r_2)^2 + 4r_1r_2}\}/2(v-2)$ . Hence

$$\rho_0 \leq \frac{(v-1)(r_1 + r_2) - \sqrt{(v-1)^2(r_1 - r_2)^2 + 4r_1r_2}}{2(v-2)} .$$

Furthermore, it can be easily shown that

$$\frac{(v-1)(r_1 + r_2) - \sqrt{(v-1)^2(r_1 - r_2)^2 + 4r_1r_2}}{2(v-2)} \leq \frac{r_1 + r_2}{2}$$

which implies that  $\rho_0 \leq (r_1 + r_2)/2$ . Thus, Theorem 2.2.2 gives a partial improvement of Theorem 2.2.1.

Corollary 2.2.2. For an  $n$ -ary BB design with parameters  $v$ ,  $b$ ,  $r_i$ ,  $k_j$  ( $i = 1, 2, \dots, v$ ;  $j = 1, 2, \dots, b$ ) in which  $C = \rho\{I_v - (1/v)G_v\}$  such that  $r_1 \leq r_2 \leq \dots \leq r_v$ ,

$$\rho \leq \frac{(v-1)(r_1+r_2) - \sqrt{(v-1)^2(r_1-r_2)^2 + 4r_1r_2}}{2(v-2)}$$

holds.

Note that if  $r_1 = r_2$ , Corollary 2.2.2 yields  $\rho \leq \min r_i (= r_1)$ .

We now compare the value,  $\rho_0$ , with an interesting value,  $\min r_i$ .

The result of this comparison will be used later.

Lemma 2.2.3. For an  $n$ -ary BB design with parameters  $v, b, r_i, k_j$  ( $i = 1, 2, \dots, v; j = 1, 2, \dots, b$ ),

$$\min r_i \leq \rho_0,$$

where  $\rho_0$  is the least positive root of  $f(\rho)$  in (2.8).

Proof. Assume, without loss of generality, that  $r_1 \leq r_2 \leq \dots \leq r_v$ . Now, consider the following matrix for any  $\epsilon$  such that  $0 < \epsilon < r_1$ .

$$\begin{aligned} D_r &= (r_1 - \epsilon)I_v + \{(r_1 - \epsilon)/v\}G_v \\ &= \text{diag}\{\epsilon, r_2 - r_1 + \epsilon, \dots, r_v - r_1 + \epsilon\} + \{(r_1 - \epsilon)/v\}G_v, \end{aligned}$$

in which case  $\text{diag}\{\epsilon, r_2 - r_1 + \epsilon, \dots, r_v - r_1 + \epsilon\}$  is positive definite and  $\{(r_1 - \epsilon)/v\}G_v$  is positive semidefinite. Thus,  $D_r = (r_1 - \epsilon)I_v + \{(r_1 - \epsilon)/v\}G_v$  is positive definite. Hence, from Proposition 2.2.1, we obtain  $\rho_0 > r_1 - \epsilon$ . Since  $\epsilon$  is arbitrary ( $0 < \epsilon < r_1$ ),  $\rho_0 \geq r_1 = \min r_i$ .

### 2.3. Conditions for Fisher's inequality

We here consider bounds on the number of blocks in a BB design.

Theorem 2.3.1. In an  $n$ -ary BB design with parameters  $v, b, r_i, k_j$  ( $i = 1, 2, \dots, v; j = 1, 2, \dots, b$ ) in which  $C = \rho\{I_v - (1/v)G_v\}$ , if  $\rho < \rho_0$ , then  $b \geq v$  holds, where  $\rho_0$  is the least positive root of  $f(\rho)$  in (2.8).

Proof. From (i) of Proposition 2.2.1, if  $\rho < \rho_0$ , then  $D_r - \rho I_v + (\rho/v)G_v (= ND_k^{-1}N')$  is positive definite. Hence  $v = \text{rank } ND_k^{-1}N' = \text{rank } N \leq b$ .

In Lemma 2.2.3, we have  $\min r_i \leq \rho_0$ . This fact together with Theorem 2.3.1 implies

Corollary 2.3.1. For an  $n$ -ary BB design with parameters  $v, b, r_i$  and  $k_j$  ( $i = 1, 2, \dots, v; j = 1, 2, \dots, b$ ) in which  $C = \rho\{I_v - (1/v)G_v\}$ , if  $\rho < \min r_i$ , then  $b \geq v$  holds.

Note that if there exists only one  $i$  such that  $\min r_i$  is attained, then the sufficient condition for Fisher's inequality to be valid can be improved to  $\rho \leq \min r_i$ .

From (ii) of Corollary 2.2.1, if  $v > \max k_j$ , then  $\rho < \min r_i$  holds and hence we have

Corollary 2.3.2. For an  $n$ -ary BB design with parameters  $v, b, r_i$  and  $k_j$  ( $i = 1, 2, \dots, v; j = 1, 2, \dots, b$ ) in which  $C = \rho\{I_v - (1/v)G_v\}$ , if  $v > \max k_j$ , then  $b \geq v$  holds.

As a characterization of a special case in which the bound of Corollary 2.1.2 is attainable, we have

Theorem 2.3.2. A binary BB design  $N$  with parameters  $v, b, r_i$  and  $k_j$  ( $\geq 2$ ) ( $i = 1, 2, \dots, v; j = 1, 2, \dots, b$ ) and  $C = \rho\{I_v - (1/v)G_v\}$  satisfies  $\rho = \min r_i$  if and only if the design is a complete block design (i.e.,  $N = E_{v \times b}$ ).

Proof. It is obvious that the sufficiency part is valid. We then consider only the necessity part. For the  $C$ -matrix of a binary BB design  $N$  such that  $r_1 \leq r_2 \leq \dots \leq r_v$ , when  $\rho = r_1$  ( $= \min r_i$ ), we have

$$\begin{aligned} ND_k^{-1}N' &= D_r - \rho I_v + (\rho/v)G_v \\ &= \begin{bmatrix} \frac{\rho}{v} & \frac{\rho}{v} & \dots & \frac{\rho}{v} \\ \frac{\rho}{v} & r_2 - \rho + \frac{\rho}{v} & & \\ \cdot & \cdot & \cdot & \frac{\rho}{v} \\ \cdot & \frac{\rho}{v} & \cdot & \cdot \\ \frac{\rho}{v} & & & r_v - \rho + \frac{\rho}{v} \end{bmatrix} = \|m_{ij}\|, \text{ say,} \end{aligned}$$

for  $i, j = 1, 2, \dots, v$ . Since  $m_{11} = m_{12} = \dots = m_{1v} (= \rho/v)$ , we get

$$(2.11) \quad 0 = \frac{n_{11}(1-n_{11})}{k_1} + \frac{n_{12}(1-n_{12})}{k_2} + \dots + \frac{n_{1b}(1-n_{1b})}{k_b} \quad \text{for } i \geq 2.$$

Since  $b \geq r_1$ , we can further assume, without loss of generality, that

$$(2.12) \quad n_{11} = n_{12} = \dots = n_{1r_1} = 1 \quad \text{and} \quad n_{1r_1+1} = \dots = n_{1b} = 0.$$

Relations (2.11) and (2.12) imply

$$n_{i1} = n_{i2} = \dots = n_{ir_i} = 1 \quad \text{for all } i = 2, 3, \dots, v.$$

Thus,

$$N = \left[ \begin{array}{c|cccc} & & & & \\ & & & & \\ E_{v \times r_1} & & & & \\ & & & & \\ & & & & \end{array} \begin{array}{c} 0 \ 0 \ \dots \ 0 \\ \\ * \\ \\ \end{array} \right] \quad (= [N_1 : N_2], \text{ say}),$$

the C-matrix of which is given by  $C = C_1 + C_2$ , where  $C_i$ 's ( $i = 1, 2$ ) are the C-matrices of  $N_i$ 's. Here,  $C = C_1 = r_1 \{I_v - (1/v)C_v\}$  and then  $C_2 = 0$ . Hence, from Lemma A,  $N_2$  cannot happen for this design  $N$ . Thus, we must have  $r_1 = b$  and then  $N = E_{v \times b}$ .

Remark 2.7. From a method of proving Theorem 2.3.2, we can also deduce that a binary BB design with parameters  $v, b, r_i, k_j$  ( $i = 1, 2, \dots, v$ ;  $j = 1, 2, \dots, b$ ) and with  $C = \rho\{I_v - (1/v)G_v\}$  satisfies  $\rho = r_i$  for some  $i$  if and only if the design is a complete block design. Furthermore, note (cf. [4]) that in an  $n$ -ary BB design  $N$  with parameters  $v, b, r$  and  $k_j$  ( $j = 1, 2, \dots, b$ ) and with  $C = \rho\{I_v - (1/v)G_v\}$ ,  $\rho = r$  holds if and only if each row of  $N$  is equal.

As seen from Remark 2.7, a BB design is usually considered in the following case, aside from trivialities: (i)  $\rho < r_i$  for all  $i$  in a binary BB design. (ii)  $\rho < r$  in an  $n$ -ary equireplicated BB design.

From Corollaries 2.1.2 and 2.3.1, and Theorem 2.3.2, we obtain an useful result:

Corollary 2.3.3. For a binary BB design with parameters  $v, b, r_i, k_j$  ( $i = 1, 2, \dots, v; j = 1, 2, \dots, b$ ) which is not of type  $E_{v \times b}$ ,  $b \geq v$  holds.



Incidentally, as more general bounds on the number of blocks which are different from Fisher's inequality, we can get

Theorem 2.3.3. For a binary BB design with parameters  $v, b, r_i, k_j$  and  $n = \sum_{i=1}^v r_i = \sum_{j=1}^b k_j$ ,

$$n - (1 - \frac{1}{\max k_j}) (\min r_i) v \leq b \leq n - (1 - \frac{1}{\min k_j}) (\max r_i) v .$$

Furthermore, if the design is equireplicated (i.e.,  $r_1 = \dots = r_v = r$ , say), then

$$(\frac{r}{\max k_j}) v \leq b \leq (\frac{r}{\min k_j}) v .$$

Proof. From a comparison of the  $i$ -th diagonal element of the  $C$ -matrix ( $= D_r - ND_k^{-1}N' = \rho\{I_v - (1/v)G_v\}$ ) of a binary BB design with parameters  $v, b, r_i, k_j$  and  $\rho = (n-b)/(v-1)$ ,

$$r_i - (\frac{n_{i1}^2}{k_1} + \dots + \frac{n_{ib}^2}{k_b}) = \frac{n-b}{v} \quad \text{for all } i \geq 1$$

i.e.,

$$(2.13) \quad r_i = \frac{n-b}{v} + \frac{n_{i1}^2}{k_1} + \dots + \frac{n_{ib}^2}{k_b}, \quad i = 1, 2, \dots, v .$$

Relation (2.13) can be evaluated in two ways. First,

$$\begin{aligned} r_i &\geq \frac{n-b}{v} + \frac{n_{i1} + \dots + n_{ib}}{\max k_j} \\ &= \frac{n-b}{v} + \frac{r_i}{\max k_j}, \end{aligned}$$

which yields  $(\min r_i) \{1 - 1/(\max k_j)\} \geq (n-b)/v$ . Hence we have



$$b \geq n - \{1 - 1/(\max k_j)\}(\min r_i)v .$$

When  $r_1 = r_2 = \dots = r_v = r$ , say, we also have

$$b \geq \{r/(\max k_j)\}v ,$$

since  $n = vr$ . Next,

$$\begin{aligned} r_i &\leq \frac{n-b}{v} + \frac{n_{i1} + \dots + n_{iv}}{\min k_j} \\ &= \frac{n-b}{v} + \frac{r_i}{\min k_j} . \end{aligned}$$

Similarly, we can get

$$b \leq n - \{1 - 1/(\min k_j)\}(\max r_i)v .$$

When  $r_1 = r_2 = \dots = r_v = r$ , say, we also have  $b \leq \{r/(\min k_j)\}v$ .

The last bound of Theorem 2.3.3 is obvious, but combinatorially interesting. Note that Theorem 2.3.3 still holds for a binary partially balanced block (PBB) design (see [7] for the definition of a PBB design).

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